

# JUNYEOP BAEK

*Ph.D. Student @ KAIST*

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## RESEARCH INTEREST

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My research interests lie in building **lifelong developmental agents** that acquire emergent cognitive capabilities through self-explored experiences, while advancing interpretability for cognitive monitoring and control, and alignment techniques. To achieve this vision, I focus on three core research questions:

- *Q1. How can we build interpretable systems to monitor and understand AI's internal cognitive processes?*  
Keywords: **World Models & Interpretability**
- *Q2. How can AI develop unique intelligence through self-explored experience rather than supervision?*  
Keywords: **Open-ended Learning & Intrinsic Motivation**
- *Q3. How can we ensure AI shares human values and develops in directions that benefit humanity?*  
Keywords: **AI Safety & Alignment**

## EDUCATION

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**Korea Advanced Institute of Science and Technology(KAIST)**

**Mar. 2025 – Present**

*Ph.D. in Computer Science - **Advisor:** Sungjin Ahn*

*Daejeon, Korea*

**Korea Advanced Institute of Science and Technology(KAIST)**

**Mar. 2023 – Feb. 2025**

*M.S. in Artificial Intelligence - **Advisor:** Sungjin Ahn*

*Daejeon, Korea*

- **Thesis:** Dreamweaver: Learning Compositional World Models from Pixels

**Hanyang University(ERICA)**

**Mar. 2014 – Feb. 2018**

*B.S. in Robot Engineering - **GPA** - 4.29 / 4.5*

*Ansan, Korea*

- *Summa Cum Laude*
- *Capstone Project1: Disaster and Rescue Robot Simulation Modeling(Darrsm) - 2nd Prize in College*
- *Capstone Project2: Walk Yourself, Toddler!(WalkYTo) - 3rd Prize in Department*

## RESEARCH EXPERIENCE

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**Visiting Researcher**

**Jun. 2025 – Aug. 2025**

*Mila-Quebec AI Institute*

*Montreal, Canada*

- Collaborating with *Yoshua Bengio*'s research group and *LawZero* team members
- Conducting research project on **Mechanistic Interpretability and Chain-of-Thought Faithfulness in LLMs**
- **Main Collaborators:** *Joumana Ghosn, Pierre-Luc St-Charles, Marc-Antoine Rondeau, Minsu Kim*

## PUBLICATIONS

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1. **Junyeob Baek**, Hosung Lee, Christopher Hoang, Mengye Ren, and Sungjin Ahn. "Discrete JEPA: Learning Discrete Token Representations without Reconstruction". In: *International Conference on Machine Learning (ICML) Tokenization Workshop* (2025).
2. Donghwan Chi, Hyomin Kim, Yoojin Oh, Yongjin Kim, Donghoon Lee, Daejin Jo, Jongmin Kim, **Junyeob Baek**, Sungjin Ahn, and Sungwoong Kim. "Slot-MLLM: Object-Centric Visual Tokenization for Multimodal LLM". *Preprint, Under Review* (2025).
3. **Junyeob Baek**, Yi-Fu Wu, Gautam Singh, and Sungjin Ahn. "Dreamweaver: Learning Compositional World Models from Pixels". In: *International Conference on Learning Representation (ICLR)* (2025).
4. Chang Chen, **Junyeob Baek**, Fei Deng, Kenji Kawaguchi, Caglar Gulcehre, and Sungjin Ahn. "PlanDQ: Hierarchical Plan Orchestration via D-Conductor and Q-Performer". In: *International Conference on Machine Learning (ICML)* (2024).

## THESIS

- **Junyeob Baek**. "Dreamweaver: Learning Compositional World Models from Pixels". Master's Thesis, KAIST, Advisor: Sungjin Ahn (Feb. 2025).

## ACADEMIC SERVICE

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### Conference Reviewer

- International Conference on Learning Representations (ICLR) 2025

### Workshop Organizer

- 2nd KAIST-Mila Prefrontal AI Workshop (6 invited speakers incl. Yoshua Bengio), [Link](#)

## TEACHING EXPERIENCE

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### Teaching Assistant

*CS377: Introduction to Reinforcement Learning, KAIST*

*Spring 2025*

- Outstanding Teaching Assistant Award recipient

## PROFESSIONAL EXPERIENCE

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### MakinaRocks

**Jun. 2021 – Jun. 2022**

*ML Research Engineer(Robotics Focused)*

*Seoul, Korea*

- **Optimization of Welding Task and Motion Planning in Vehicle Manufacturing Process**
  - \* Challenges: 1. Large-scale and high complexity in Optimization Problem. 2. Required high-accuracy planning in highly cluttered environments. 3. Required tight Time Window for control
  - \* [*Contribution 1*] GA-based Multi-objective Optimization Module for Welding-point Assignment
  - \* [*Contribution 2*] Multi-Robot Interlock Scheduling System with Swept-volume-based collision detection

### Syscon, Co., Ltd.

**Dec. 2017 – Jun. 2021**

*Robotics Software Engineer/Research Strategy Manager*

*Incheon, Korea*

- **AMR Navigation System Design & Product Development**
- [*Field Exp.*] **Successful Deployment for Smart Factory Project**
  - \* More than 300 delivery tasks per day with 14 robots
- [*Research Exp.*] **Learning-based High-accuracy Object Pose Estimator(Dock Pose Estimation)**
- [*Research Exp.*] **Distilled Meta Policy Navigation System for Multi-behavior Skillset and its Strategies**